

# Stability Assessment for Trees and other Supervised Statistical Learning Results

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**University of  
Zurich** <sup>UZH</sup>

Trees and Co

CART

MOB

Random Forests

Stability of trees

Tree structure

`stablelearner`

Variable selection

Cutpoint selection

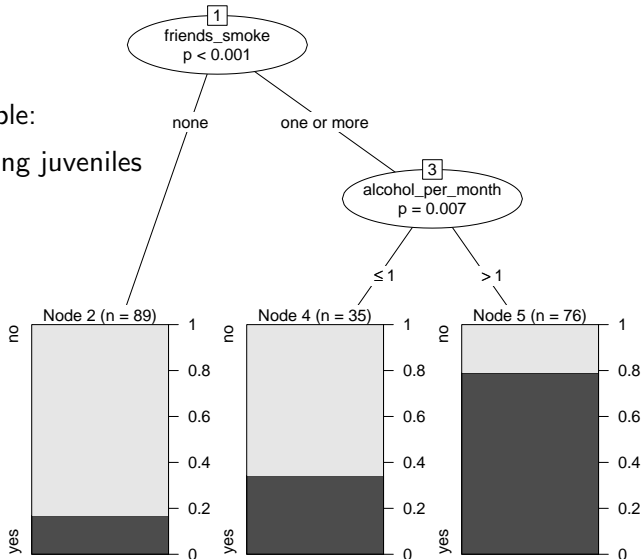
Stability for  
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# Classification and regression trees (CART)

Example:  
Smoking juveniles



R-package party (Hothorn, Hornik, Strobl and Zeileis)

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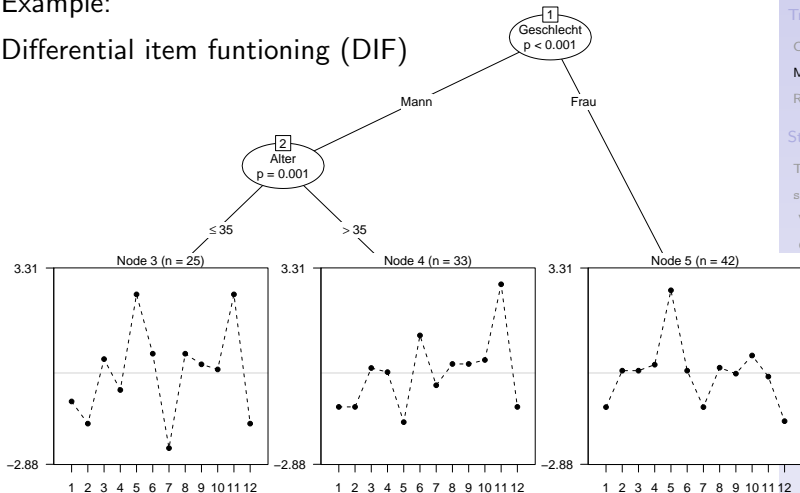
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# Model based recursive partitioning (MOB)

Example:

Differential item functioning (DIF)



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references

R-package psychotree (Zeileis, Strobl, Wickelmaier,  
Komboz, Kopf)

# Trees are...

+ easy to interpret

- instable

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# Trees are...

- + easy to interpret (really?)
- instable

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# Trees are...

- + easy to interpret (really?)
- instable (and no means of inference for complete tree)

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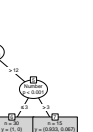
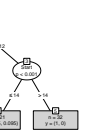
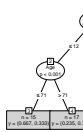
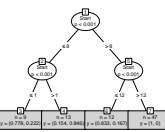
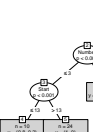
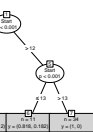
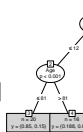
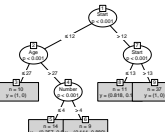
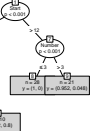
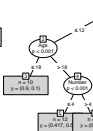
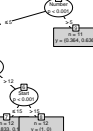
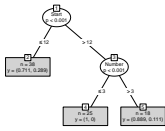
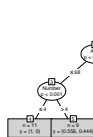
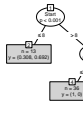
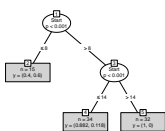
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# Forests are...

- + stable (for predictions)
- no longer interpretable

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# Forests are...

+ stable (for predictions)

– no longer interpretable

⇒ when is a single tree safe to interpret?

# Stability assessment for trees

- ▶ resample from the learning data  
(bootstrap/subsampling/sample splitting/jackknife)
- ▶ fit trees on all samples  $\Rightarrow$  can look quite different

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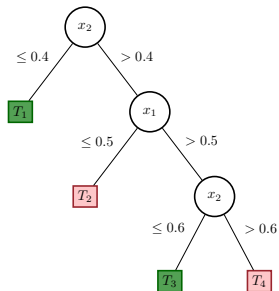
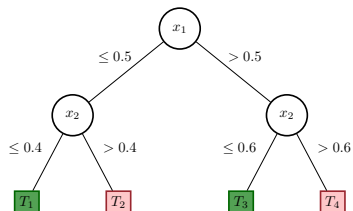
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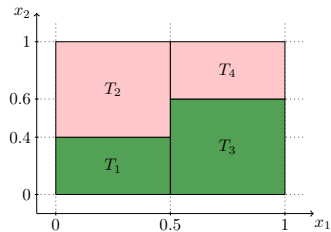
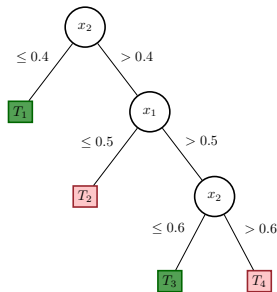
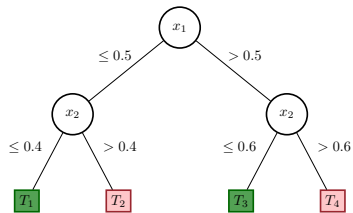
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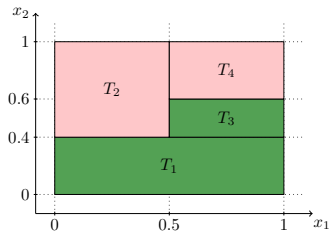
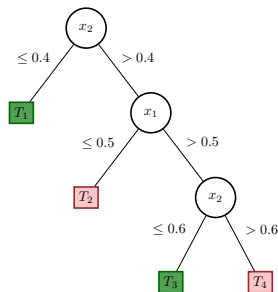
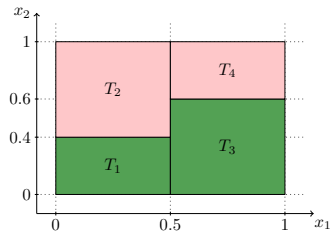
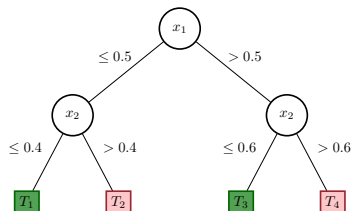
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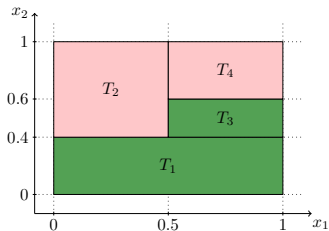
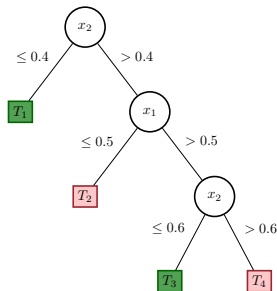
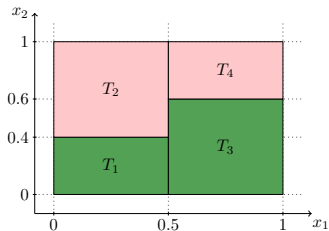
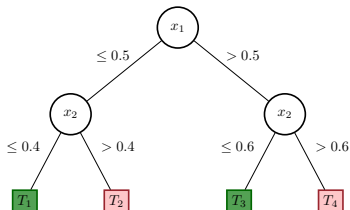
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# Tree structure – totally overrated!



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# Stability assessment for trees

- ▶ resample from the learning data  
(bootstrap/subsampling/sample splitting/jackknife)
- ▶ fit trees on all samples  $\Rightarrow$  can look quite different

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# Stability assessment for trees

- ▶ resample from the learning data  
(bootstrap/subsampling/sample splitting/jackknife)
- ▶ fit trees on all samples  $\Rightarrow$  can look quite different
- ▶ create summary statistics and plots for
  - ▶ variable selection
  - ▶ cutpoint selection

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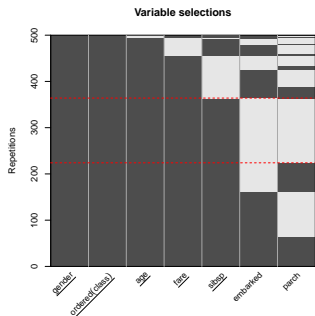
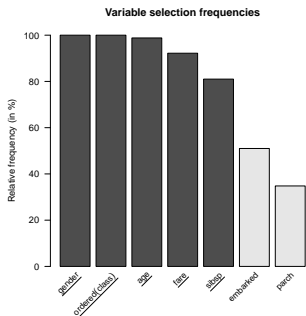


## Stability assessment for trees

```

> mytree <- ctree(y ~ x1 + x2 + ..., data = ...)
> stab_mytree <- stabletree(mytree, B = 500)
> barplot(stab_mytree)      > image(stab_mytree)

```



R-package `stablelearner` (Philipp, Strobl, Zeileis, Rusch, Hornik)

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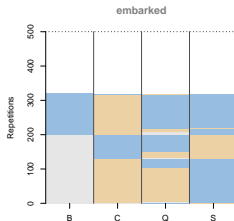
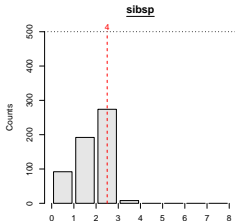
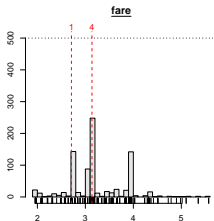
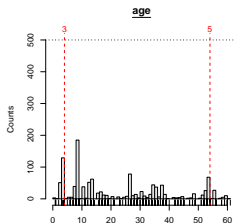
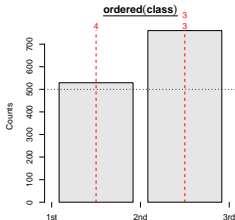
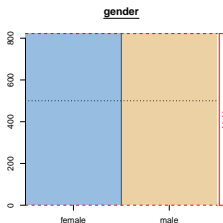
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# Stability assessment for trees

```
> plot(stab_mytree)
```



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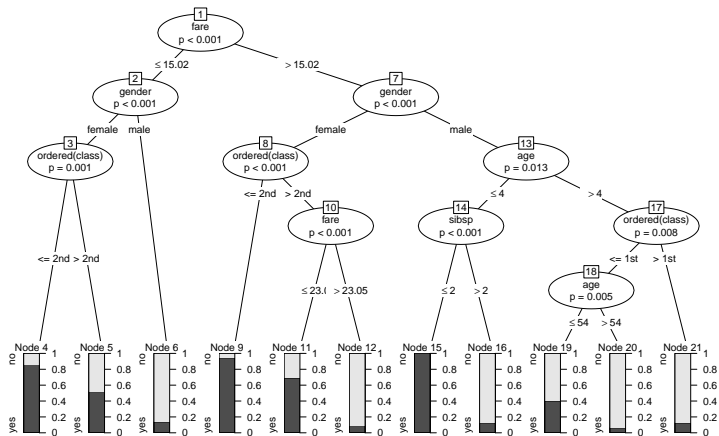
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# Stability assessment for trees

> plot(mytree)



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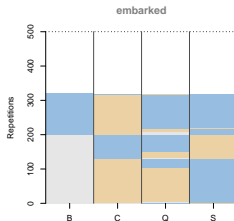
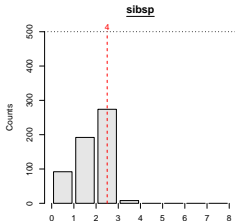
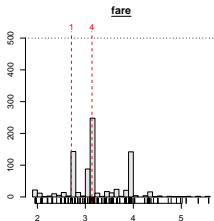
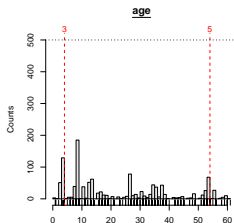
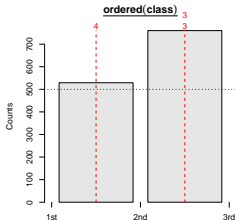
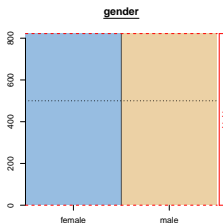
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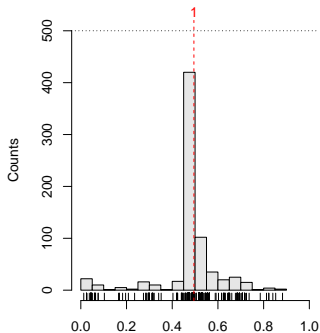
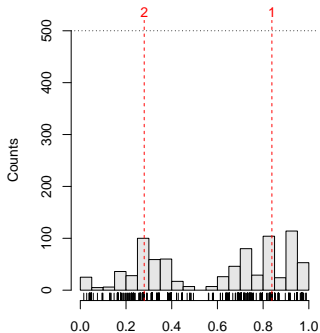
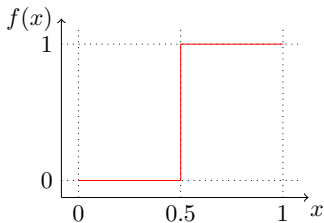
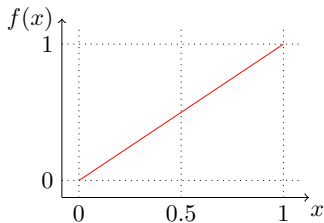
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- ▶ structural vs. semantic stability

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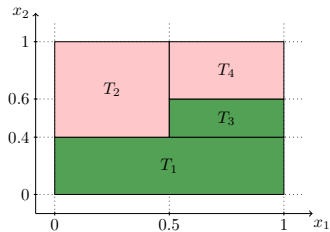
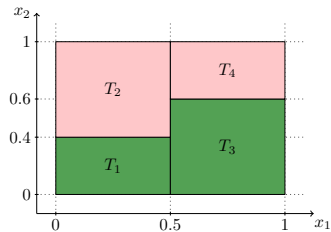
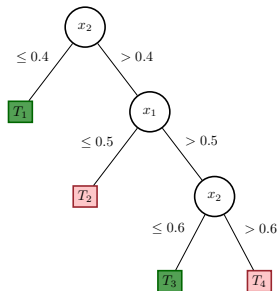
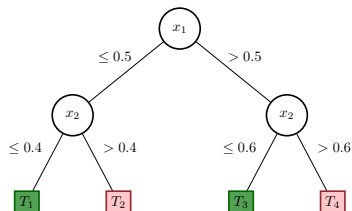
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- ▶ structural vs. semantic stability

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# Stability assessment in general

- ▶ structural vs. semantic stability  $\Rightarrow$  compare predictions

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# Stability assessment in general

- ▶ structural vs. semantic stability  $\Rightarrow$  compare predictions
- ▶ stability depends on
  - ▶ algorithm, model
  - ▶ data generating process

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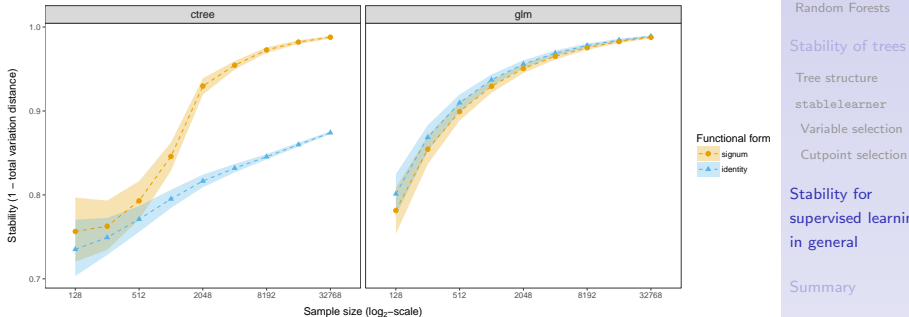
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# Match between algorithm and dgp



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# Stability assessment in general

- ▶ structural vs. semantic stability  $\Rightarrow$  compare predictions
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# Stability assessment in general

- ▶ structural vs. semantic stability  $\Rightarrow$  compare predictions
- ▶ stability depends on
  - ▶ algorithm, model
  - ▶ data generating process
  - ▶ sample size
  - ▶ resampling strategy, distance measure
- ▶ works for real and simulation settings

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# Example: Benchmark study

stability and prediction accuracy of ctree

Data set	$n$	$p$	$K$	Stability		Accuracy		CPU time [sec]
				Median	IQR	Median	IQR	
Iris	150	4	3	0.956	0.048	0.919	0.146	4.7
Breast Cancer	699	9	2	0.933	0.029	0.864	0.080	13.4
Titanic	1317	7	2	0.925	0.027	0.561	0.086	13.6
Ionosphere	351	34	2	0.900	0.058	0.788	0.132	10.8
Pima	768	8	2	0.835	0.036	0.403	0.130	13.8
Satellite	6435	36	6	0.819	0.013	0.363	0.025	631.3
Sonar	208	60	2	0.728	0.098	0.412	0.231	12.6
Vehicle	846	18	4	0.723	0.050	0.552	0.084	50.3
Glass	214	9	6	0.694	0.107	0.219	0.185	12.9

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framework for assessing the stability of trees

- ▶ descriptive statistics and plots for variable and cutpoint selection
- ▶ works for all kinds of trees and MOBs  
(incl. `ctree`, `(g)lmtree`, `raschtree` etc. via `partykit`)

framework for assessing the stability of supervised learning

- ▶ one number/distribution for measuring stability
- ▶ works for classification and regression problems
- ▶ future work: extend to MOB

available in R-package `stablelearner` (Philipp, Strobl, Zeileis, Rusch, Hornik)

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- Philipp M, Zeileis A, Strobl C (2016). A toolkit for stability assessment of tree-based learners. In Colubi et al. (Eds.) *Proceedings of COMPSTAT 2016 – 22nd International Conference on Computational Statistics*, 315–325.
- Philipp M, Rusch T, Hornik K, Strobl C (2018). Measuring the stability of results from statistical learning. *Journal of Computational and Graphical Statistics* (forthcoming).
- Strobl C, Malley J, Tutz G (2009). An Introduction to Recursive Partitioning: Rationale, Application and Characteristics of Classification and Regression Trees, Bagging and Random Forests. *Psychological Methods*, **14**(4), 323–348.

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# Stability assessment for trees

```
> summary(stab_mytree)
```

	freq	*	mean	*
gender	1.000	1	1.644	2
ordered(class)	1.000	1	2.578	3
age	0.988	1	2.316	2
fare	0.922	1	1.676	2
sibsp	0.810	1	1.132	1
embarked	0.510	0	0.638	0
parch	0.348	0	0.444	0

(\* = original tree)

freq: variable selection frequency

mean: average number of appearances per tree

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# Stability assessment in general

for  $b = 1, \dots, B$

- (1) Generate two learning samples  $\mathcal{L}'_b$  and  $\mathcal{L}''_b$  plus an evaluation sample  $\mathcal{E}_b$  by sampling from  $\mathcal{F}$  that is a proxy for  $\mathbb{P}_Z$ . To do this in practice, the plug-in principle can be used. Thus, for the

$$\begin{aligned} \text{real data problem: } \mathcal{F} &\hat{=} \widehat{F}_n, \\ \text{simulation study problem: } \mathcal{F} &\hat{=} \mathbb{P}_Z, \end{aligned}$$

where  $\widehat{F}_n$  is an approximation of  $\mathbb{P}_Z$  that represents the DGP well when  $n$  is large.

- (2) Generate the results  $r_{\mathcal{A}, \mathcal{M}}(x; \mathcal{L}'_b)$  and  $r_{\mathcal{A}, \mathcal{M}}(x; \mathcal{L}''_b)$  by training the algorithm on both learning samples.
- (3) Compute  $s(\hat{y}'_b, \hat{y}''_b)$  using the evaluation sample  $\mathcal{E}_b$ .

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